

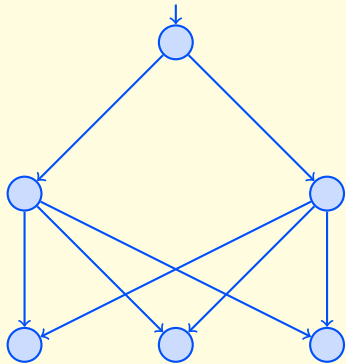
# Parity Games with Imperfect Information on Graphs of Bounded Complexity

Bernd Puchala   Roman Rabinovich

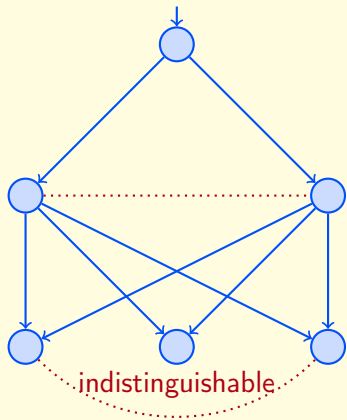
RWTH Aachen University

May 2010

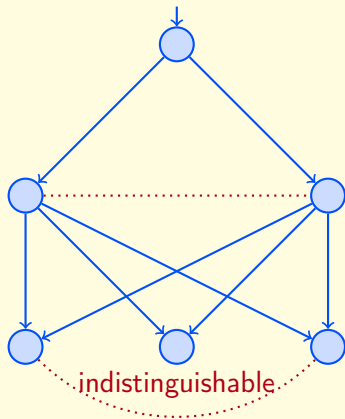
# Imperfect Information



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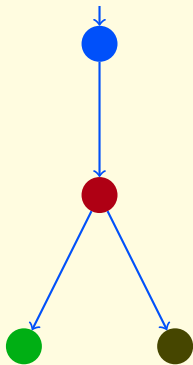
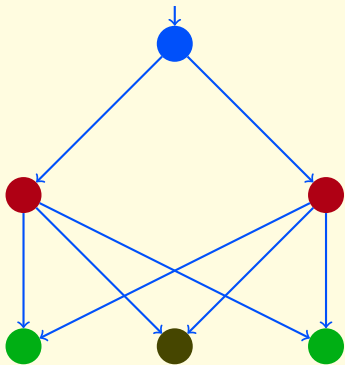


# Imperfect Information

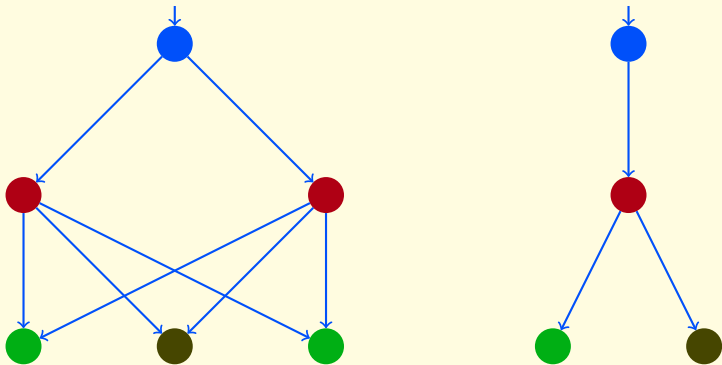


- ▶ **Indistinguishable** vertices build an **information set**.
- ▶ Add colours to the vertices (for parity condition).
- ▶ Technical subtleties:
  - ▶ Edges are labeled.
  - ▶ Edge labels may be indistinguishable.
  - ▶ Edge labels compatible with information sets.
  - ▶ Colours compatible with information sets.
  - ▶ Start vertex distinguishable from all.
  - ▶ Mark vertices of Player 0.

# Powerset Construction



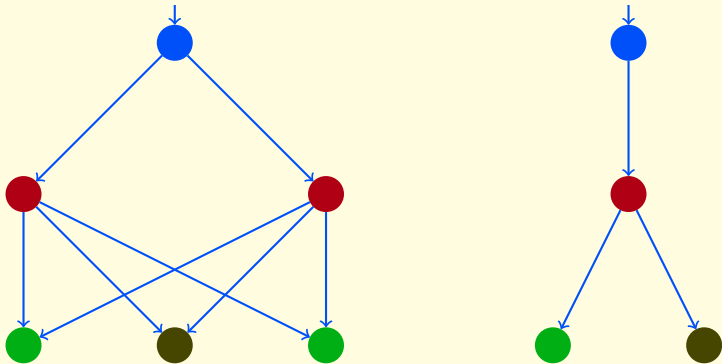
# PowerSet Construction



## Theorem (Reif)

*Player 0 wins from  $v$  in  $G^{imperf} \Leftrightarrow$  Player 0 wins from  $\{v\}$  in  $G^{perf}$*

# Powerset Construction



## Theorem (Reif)

*Player 0 wins from  $v$  in  $G^{imperf} \Leftrightarrow$  Player 0 wins from  $\{v\}$  in  $G^{perf}$*

## Lemma

*Path  $\text{blue} \rightarrow \text{red} \rightarrow \text{green}$  in  $G^{imperf} \Leftrightarrow$  path  $\text{blue} \rightarrow \text{red} \rightarrow \text{green}$  in  $G^{perf}$ .*

# Complexity Measures

Motivation:

- ▶ solve parity games in P despite imperfect information,
- ▶ but:
  - ▶ not known whether PARITY is in P
  - ▶ the powerset graph can be exponentially bigger

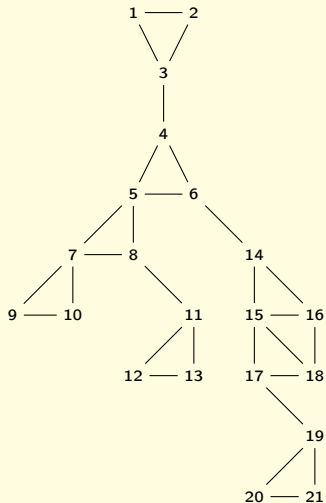
Hope: on **simple** graphs PARITY in P (like without imperfect information)  
⇒ Need to measure **complexity** of a graph.



# Measures:

- ▶ tree-width (undirected graphs) + path-width  $\oplus$
- ▶ directed tree-width ?
- ▶ DAG-width + directed path-width  $\oplus$
- ▶ Kelly-width  $\oplus$
- ▶ entanglement  $\oplus$
- ▶ ... (not considered here)

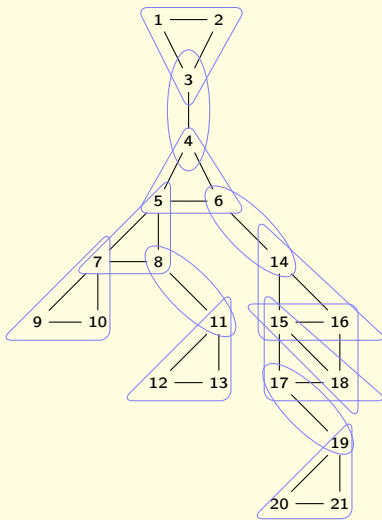
# Tree-width: Tree Decomposition



simple = like a tree

complex = like a grid

# Tree-width: Tree Decomposition



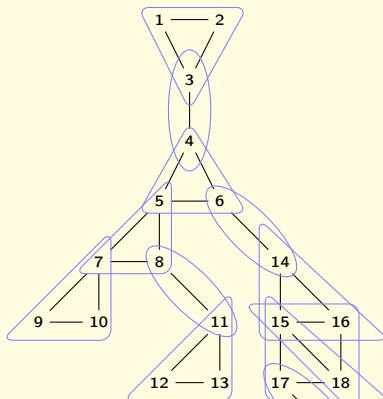
simple = like a tree

complex = like a grid

Bags:

- ▶ treelike connected
- ▶ contain every vertex
- ▶ contain every edge
- ▶ bags with vertex  $v$  induce one subtree

# Tree-width: Tree Decomposition



simple = like a tree

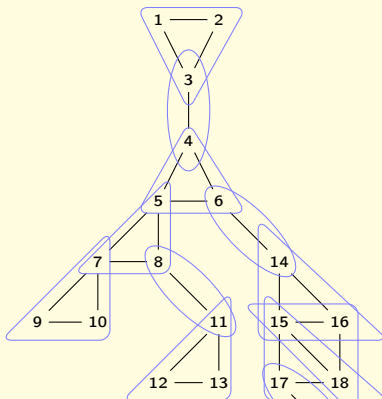
complex = like a grid

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**Tree-width:** minimal size of the greatest bag – 1

# Tree-width: Tree Decomposition



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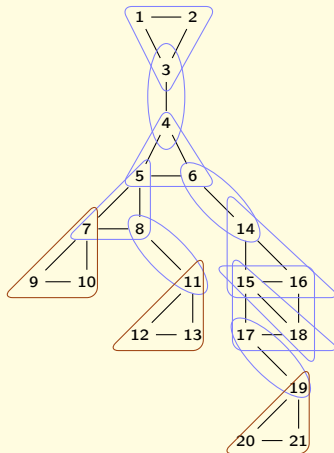
Bags:

- ▶ treelike connected
- ▶ contain every vertex
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- ▶ bags with vertex  $v$  induce one subtree

Path-width: the same, but path instead of tree

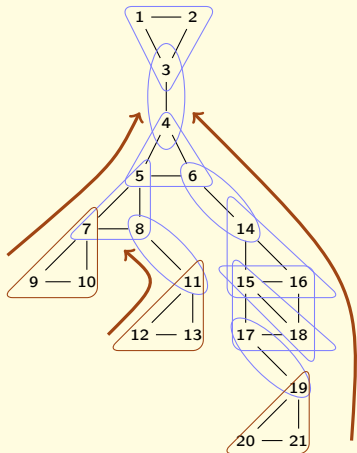
# Dynamic Programming on Tree Decomposition

- ▶ small bags  $\Rightarrow$  arbitrary computations on leaf bags
- ▶ use: connections between bags are simple: treelike!
- ▶  $\Rightarrow$  PARITY in P

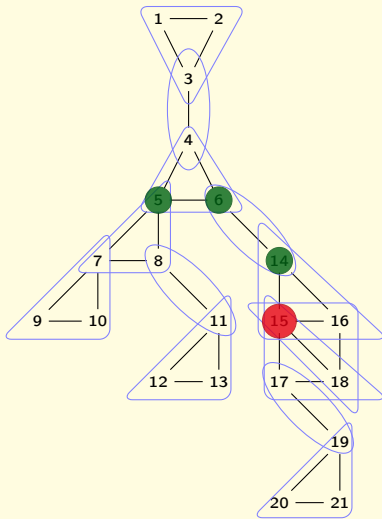


# Dynamic Programming on Tree Decomposition

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- ▶  $\Rightarrow$  PARITY in P



# Game Theoretical Characterisation

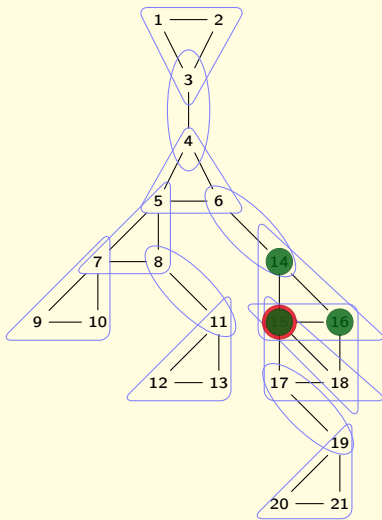


Game rules:

- ▶  $k$  Cops, one Robber
- ▶ Robber runs along cop free paths
- ▶ Cops fly
- ▶ Cops want to capture Robber



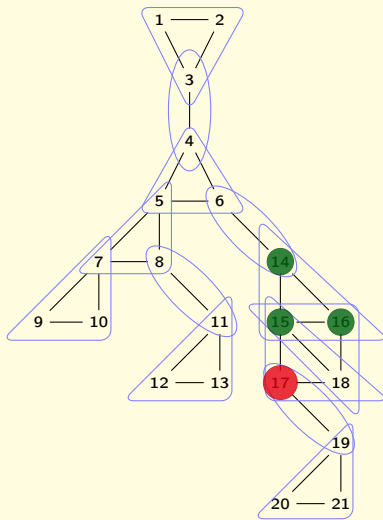
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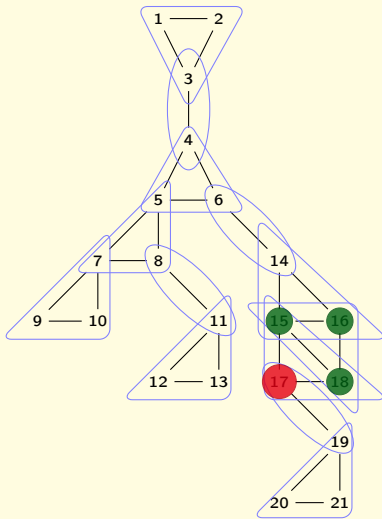
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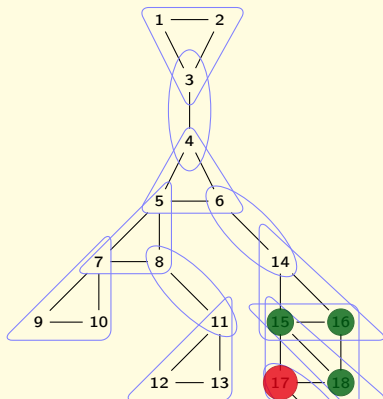
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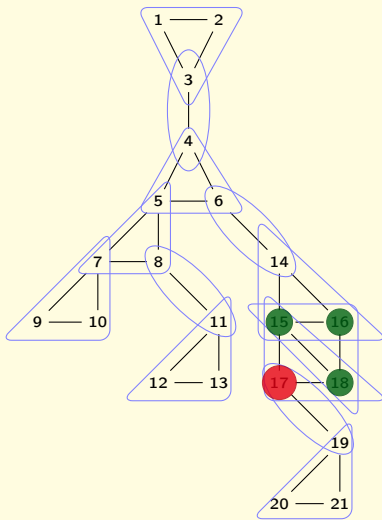


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Tree-width = minimal number cops (monotonously) capturing Robber - 1

# Game Theoretical Characterisation



Game rules:

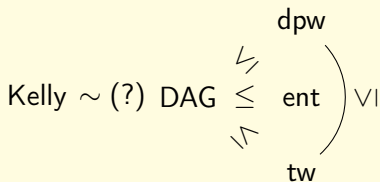
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Path-width:

the same,  
but robber invisible.

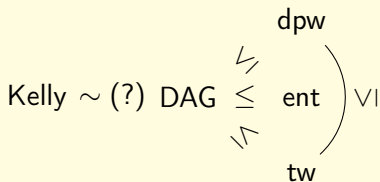
# On Directed Graphs

- ▶ DAG-width game (Berwanger et al. 2006, Obdržálek 2006)
  - ▶ like before, but Robber runs along **directed** paths + **monotonicity**
  - ▶ if DAG-width bounded (+ directed path-width): PARITY in P  $\oplus$
- ▶ Kelly-width (Kreutzer, Hunter 2007)
  - ▶ like DAG-width, but Robber is **inert** and **invisible** + **monotonicity**
  - ▶ if Kelly-width bounded: PARITY in P  $\oplus$
- ▶ directed tree-width (Johnson et al. 2001)
  - ▶ like DAG-width, but Robber doesn't leave her SCC
  - ▶ if directed tree-width bounded: PARITY in P ?
- ▶ entanglement (Grädel, Berwanger 2005)
  - ▶ like DAG-width, but Robber slow and cops restricted
  - ▶ if entanglement bounded: PARITY in P  $\oplus$



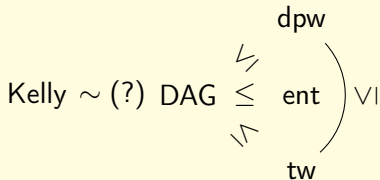
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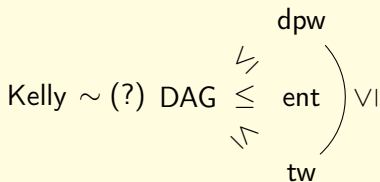
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  - ▶ if entanglement bounded: PARITY in P  $\oplus$



# Unbounded Imperfect Information

# Measures Grow Exponentially

## Theorem

*Exists  $G^{imperf}$  simple, but  $G^{perf}$  complex (w.r.t. all our measures).*

- ▶ very large information sets
- ▶  $G^{perf}$  contains a huge undirected grid (grids are complex!)

## Theorem

*Reachability: EXPTIME-hard even if entanglement  $\leq 2$  and directed path-width  $\leq 3$ . (Refine original proof for hardness by Reif.)*

## Theorem

*Reachability: PSPACE-hard even on DAGs.*

$\Rightarrow$  need to bound size of information sets

## Bounded Imperfect Information

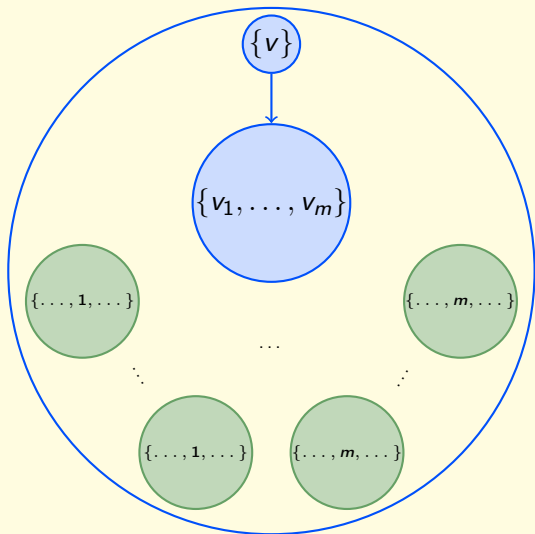
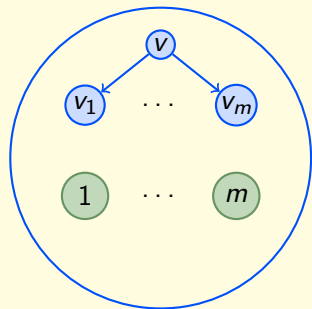
# General Procedure

- ▶ show  $\text{measure}(G^{imperf}) \leq k$ ,  $|\text{information sets}| \leq r$   
 $\Rightarrow \text{measure}(G^{perf}) \leq f(k, r)$
- ▶ then for appropriate measures:  
if  $\text{measure}(G^{imperf}) \leq k$  and  $|\text{information sets}| \leq r$   
then PARITY in P

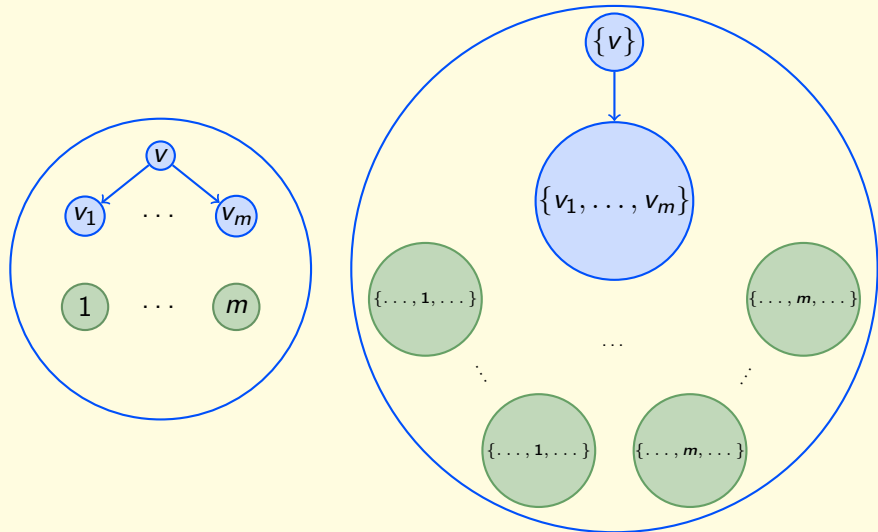
# How Measures Behave

- ▶ tree-width:  $\ominus \text{tw}(G^{imperf}) = 2$ , but  $\text{tw}(G^{perf})$  unbounded
- ▶ entanglement:  $\ominus \text{ent}(G^{imperf}) = 2$ , but  $\text{ent}(G^{perf})$  unbounded
- ▶ *non-monotone* DAG-width:  $\oplus f(k, r) = k \cdot r \cdot 2^{r-1}$ 
  - ▶ not an appropriate measure
  - ▶ if every information set is an SCC:  $\oplus, f(k, r) = k \cdot r^2 \cdot 2^{r-1}$
  - ▶ if every |information set|  $\leq 2$ :  $\oplus, f(k, r)$  bounded
- ▶ DAG-width: ? good hope that  $\oplus$
- ▶ directed path-width:  $\oplus, f(k, r) = k \cdot 2^{r-1}$
- ▶ Kelly-width: ? (idea doesn't work: inert robber)
- ▶ directed tree-width: ? (doesn't work: robber cannot leave her SCC)

# General Proof Idea for Boundedness of Measures



# General Proof Idea for Boundedness of Measures

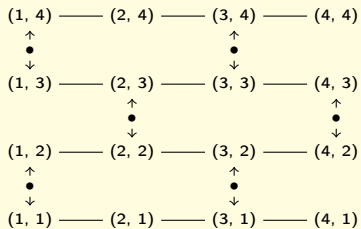
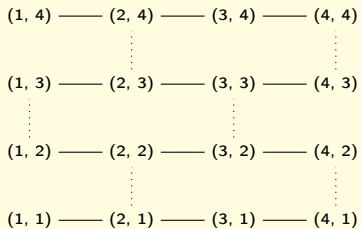


Lemma

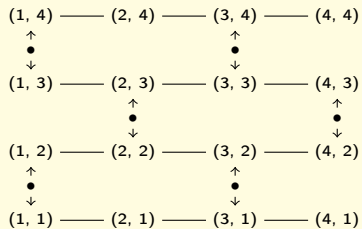
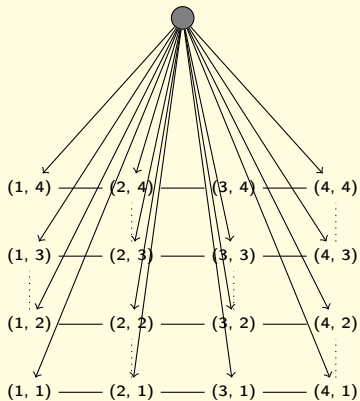
Path  $\bullet \rightarrow \bullet \rightarrow \bullet$  in  $G^{imperf} \Leftrightarrow$  path  $\bullet \rightarrow \bullet \rightarrow \bullet$  in  $G^{perf}$ .



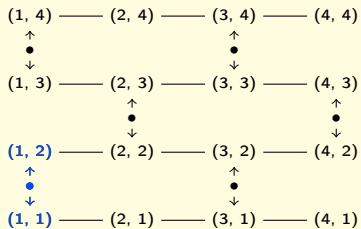
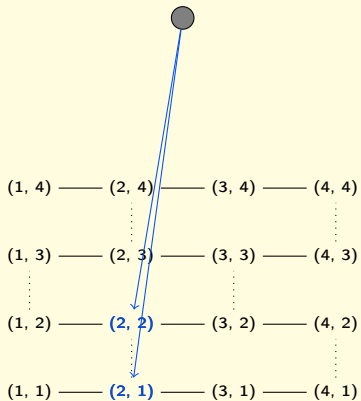
# Tree-width Grows Unbounded



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## Future Work + Work in Progress

- ▶ (monotone) DAG-width of  $G^{imperf}$  bounded
- ↓
- (monotone) DAG-width of  $G^{perf}$  bounded
- ▶ clique-width (measure for regularity of a graph)