# Algorithmic Model Theory <br> SS 2010 

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## 1 The classical decision problem for FO

The classical decision problem for first-order logic was considered the main problem of mathematical logic by Hilbert and Ackermann and its undecidability was shown by Church and Turing.

The Entscheidungsproblem is solved when we know a procedure that allows for any given logical expression to decide by finitely many operations its validity or satisfiability. [...] The Entscheidungsproblem must be considered the main problem of mathematical logic.
(D. Hilbert and W. Ackermann, 1928)

We introduce the classical decision problem for first-order logic, for which we present three equivalent formulations. The importance of the decision problem for first-order logic results from the fact that first-order logic provides a framework to express almost all aspects of mathematics.

Satisfiability: Construct an algorithm that decides for any given formula of FO whether it has a model.
Validity: Construct an algorithm that decides for any given formula of FO whether it is valid, i.e. whether it holds in all models where it is defined.
Provability: Construct an algorithm that decides for any given formula $\psi$ of FO whether $\vdash \psi$, meaning $\psi$ is provable from the empty set of axioms in some formal system, e.g. sequential calculus.
Since $\psi$ is satisfiable if and only if $\neg \psi$ is not valid, satisfiability and validity are equivalent problems with respect to computability. The equivalence with provability is a much more intricate result and in fact a consequence of the following

Theorem 1.1 (Completeness Theorem (Gödel)). For any given set of sentences $\Phi \subseteq \mathrm{FO}(\tau)$ and any sentence $\psi \in \mathrm{FO}(\tau)$ it holds that

$$
\Phi \models \psi \Longleftrightarrow \Phi \vdash \psi ;
$$

in particular $\varnothing \models \psi \Leftrightarrow \varnothing \vdash \psi$.
As a direct consequence we get the following
Theorem 1.2. The set of valid first-order formulae is recursively enumerable.

### 1.1 Basic notions on decidability

In our formulation of the decision problem it was not precisely specified what an algorithm is. It was not until the 1930s that Church and Kleene, Gödel and Turing provided a precise definition of an abstract algorithm. Their approaches are today known to be equivalent. We introduce the concept of a Turing machine.
Definition 1.3. A Turing machine (TM) $M$ is a 6 -tuple
$M=\left(Q, \Sigma, \Gamma, q_{0}, F, \delta\right)$, where

- $Q$ denotes a finite set of states,
- $\Sigma, \Gamma$ denote finite alphabets, where $\Sigma$ is the working alphabet with a special blank symbol $\square \in \Sigma$,
- $\Gamma \subseteq \Sigma \backslash\{\square\}$ is the input alphabet,
- $q_{0} \in Q$ denotes the initial state,
- $F \subseteq Q$ is the set of final states and
- $\delta:(Q \backslash F) \times \Sigma \rightarrow Q \times \Sigma \times\{-1,0,1\}$ is the transition function.

A configuration is an element $C=\left(q, p, w=w_{0} w_{1} \ldots w_{k}\right) \in Q \times \mathbb{N} \times \Sigma^{*}$. The transition function $\delta$ induces a partial function on the set of all configurations

$$
C \mapsto \operatorname{Next}(C),
$$

where for $\delta\left(q, w_{p}\right)=\left(q^{\prime}, a, m\right)$, the successor configuration of $C$ is defined as $\operatorname{Next}(\mathrm{C})=\left(q^{\prime}, p+m, w_{0} \ldots w_{p-1} a w_{p+1} \cdots w_{k}\right)$. A computation of the TM $M$ on an input word $x \in \Gamma^{*}$ is a configuration
sequence
$C_{0}, C_{1}, \ldots$
where $C_{0}=C_{0}(x):=\left(q_{0}, 0, x\right)$ is the input configuration and $C_{i+1}=$ $\operatorname{Next}\left(\mathrm{C}_{\mathrm{i}}\right)$ for all $i$.
$M$ halts on $x$ if the computation of $M$ on $x$ is finite, i.e. ends in a final configuration $C_{f}=(q, p, w)$ with $q \in F$.

The language accepted by $M$ is
$L(M):=\left\{x \in \Gamma^{*}: M\right.$ halts on $\left.x\right\}$.
$M$ computes a partial function $f_{M}: \Gamma^{*} \rightarrow \Sigma^{*}$ with domain $L(M)$ such that $f_{M}(x)=y$ if and only if the computation of $M$ on $x$ ends in $(q, p, y)$ for some $q \in F, y \in \Sigma^{*}$ and $p \in \mathbb{N}$.

Definition 1.4. A Turing acceptor is a Turing machine $M$ with $F=$ $F^{+} \hookleftarrow F^{-}$where $M$ accepts $x$ if the computation of $M$ on $x$ ends in a state in $F^{+} . M$ rejects $x$ if the computation of $M$ on $x$ ends in a state in $F^{-}$.

## Definition 1.5.

- $L \subseteq \Gamma^{*}$ is recursively enumerable (r.e.) if there exists a TM $M$ with $L(M)=L$.
- $L \subseteq \Gamma^{*}$ is co-recursively enumerable (co-r.e.) if $\bar{L}:=\Gamma^{*} \backslash L$ is r.e..
- A (partial) function $f: \Gamma^{*} \rightarrow \Sigma^{*}$ is (Turing) computable if there is a TM $M$ with $f_{M}=f$.
- $L \subseteq \Gamma^{*}$ is decidable if there is a Turing acceptor $M$ such that for all $x \in \Gamma^{*}$

$$
\begin{aligned}
& x \in L \Rightarrow M \text { accepts } x \\
& x \notin L \Rightarrow M \text { rejects } x
\end{aligned}
$$

or, equivalently, $L$ is decidable if its characteristic function $\chi_{L}: \Gamma^{*} \rightarrow\{0,1\}$ is Turing computable.

Theorem 1.6. A language $L \subseteq \Gamma^{*}$ is decidable if and only if $L$ is r.e. and co-r.e.

Definition 1.7. Let $A \subseteq \Gamma^{*}, B \subseteq \Sigma^{*}$. We say that $A$ is (many-to-one) reducible to $B, A \leq B$, if there is a total computable function $f: \Gamma^{*} \rightarrow \Sigma^{*}$ such that for all $x \in \Gamma^{*}$ we have $x \in A \Leftrightarrow f(x) \in B$.

## Lemma 1.8.

- $A \leq B, B$ decidable $\Rightarrow A$ decidable
- $A \leq B, B$ r.e. $\Rightarrow A$ r.e.
- $A \leq B, A$ undecidable $\Rightarrow B$ undecidable.

There surely are undecidable languages since there are only countably many Turing machines but uncountably many languages. Unfortunately, among these languages there are quite relevant classes of languages. For example we cannot even decide whether a TM halts on a given input.

Definition 1.9 (Halting Problems). The general halting problem is defined as

$$
H:=\{\rho(M) \# \rho(x): M \text { Turing machine, } x \in L(M)\}
$$

where $\rho(M)$ and $\rho(x)$ are encodings of the TM $M$ and the input $x$ over a fixed alphabet $\{0,1\}$ such that the computation of $M$ on $x$ can be reconstructed from the encodings $\rho(M)$ and $\rho(x)$ in an effective way.

There is a universal TM $U$ which, given $\rho(M)$ and $\rho(x)$, simulates the computation of $M$ on $x$ and halts if and only if $M$ halts on $x$. Thus, $L(U)=H$ from which we conclude that $H$ is r.e..

We introduce two special variants of the halting problem

- Self-application problem

$$
H_{0}:=\{\rho(M): \rho(M) \in L(M)\}
$$

- Halting on the empty word

$$
H_{\varepsilon}:=\{\rho(M): \varepsilon \in L(M)\}
$$

Theorem 1.10. $H, H_{0}, H_{\varepsilon}$ are undecidable.

## Proof.

- $H_{0}$ is not co-r.e. and thus undecidable. Otherwise $\bar{H}_{0}=L\left(M_{0}\right)$ for some TM $M_{0}$. Then

$$
\rho\left(M_{0}\right) \in H_{0} \Leftrightarrow M_{0} \text { halts on } \rho\left(M_{0}\right) \Leftrightarrow \rho\left(M_{0}\right) \in \bar{H}_{0} \text {. }
$$

- $H_{0}$ is a special case of $H, H_{0} \leq H$, and thus $H$ is undecidable.
- We can reduce $H$ to $H_{\varepsilon}$, thus $H_{\varepsilon}$ is undecidable.

As a consequence of the next theorem we cannot algorithmically prove whether a program computes a given function, i.e. we cannot algorithmically prove the correctness of a program. Note that this does not mean that we cannot prove the correctness of a single given program. Instead the statement is that we cannot do so algorithmically for all programs.

Theorem 1.11 (Rice). Let $\mathcal{R}$ be the set of all computable functions and let $S \subseteq \mathcal{R}$ be a set of computable functions such that $S \neq \varnothing$ and $S \neq \mathcal{R}$. Then code $(S):=\left\{\rho(M): f_{M} \in S\right\}$ is undecidable.

Proof. Let $\Uparrow$ be the everywhere undefined function, i.e. $\operatorname{Def}(\Uparrow)=\varnothing$. Obviously, $\Uparrow$ is computable. Assume that $\Uparrow \notin S$ (otherwise consider $\mathcal{R} \backslash S$ instead of $S$. Clearly if code $(\mathcal{R} \backslash S)$ is undecidable then so is code(S).)

As $S \neq \varnothing$, there exists a function $f \in S$. Let $M_{f}$ be a TM that computes $f$, i.e. $f_{M_{f}}=f$. We define a reduction $H_{\varepsilon} \leq \operatorname{code}(S)$ by describing a total computable function $\rho(M) \mapsto \rho\left(M^{\prime}\right)$ such that
$M$ halts on $\varepsilon \Leftrightarrow f_{M^{\prime}} \in S$.
Specifically, given $\rho(M)$, we construct the encoding of a TM $M^{\prime}$ which, given an input $x$, proceeds as follows:

- first simulate $M$ on $\varepsilon$ (i.e. apply the universal TM $U$ to $\rho(M) \# \varepsilon$ );
- then simulate $M_{f}$ on $x$ (i.e. apply the universal TM $U$ to $\left.\rho\left(M_{f}\right) \# \rho(x)\right)$.

It is clear that the reduction function is computable. Furthermore, if $M$ halts on $\varepsilon$ then $f_{M^{\prime}}(x)=f(x)$ for all inputs $x$, i.e. $f_{M^{\prime}}=f$, so $f_{M^{\prime}} \in S$. If $M$ does not halt on $\varepsilon$ then $M^{\prime}$ does not halt on $x$ for any $x$, i.e. $f_{M^{\prime}}=\Uparrow$, so $f_{M^{\prime}} \notin S$.
Q.e.D.

Definition 1.12 (Recursive inseparability). Let $A, B \subseteq \Gamma^{*}$ be two disjoint sets. We say that $A$ and $B$ are recursively inseparable if there exists no recursive set $C \subseteq \Gamma^{*}$ such that $A \subseteq C$ and $B \cap C=\varnothing$.

Example. $(A, \bar{A})$ are recursively inseparable if and only if $A$ is undecidable.

Lemma 1.13. Let $A, B \subseteq \Gamma^{*}, A \cap B=\varnothing$ be recursively inseparable. Let $X, Y \subseteq \Sigma^{*}, X \cap Y=\varnothing$, and let $f$ be a total computable function such that $f(A) \subseteq X$ and $f(B) \subseteq Y$. Then $X$ and $Y$ are recursively inseparable.

Proof. Assume there exists a decidable set $Z \subseteq \Sigma^{*}$ such that $X \subseteq Z$ and $Y \cap Z=\varnothing$. Consider $C=\left\{x \in \Gamma^{*}: f(x) \in Z\right\}$. $C$ is decidable, $A \subseteq C, B \cap C=\varnothing$, thus $C$ separates $A, B$.
Q.E.D.

Notation: We write $(A, B) \leq(X, Y)$ if such a function $f$ exists.
Example. $(A, \bar{A}) \leq(B, \bar{B}) \Leftrightarrow A \leq B$.
As a preparation to prove Trakhtenbrot's theorem, we consider a refinement of $H_{\varepsilon}$

$$
\begin{aligned}
& H_{\varepsilon}^{+}:=\{\rho(M): M \text { accepts } \varepsilon\} \\
& H_{\varepsilon}^{-}:=\{\rho(M): M \text { rejects } \varepsilon\} \\
& H_{\varepsilon}^{\infty}:=\{\rho(M): \text { the computation of } M \text { on } \varepsilon \text { is infinite }
\end{aligned}
$$

$$
\text { and does not cycle.\} }
$$

$H_{0}^{+}, H_{0}^{-}, H_{0}^{\infty}$ are defined analogously, with respect to selfapplication.

Theorem 1.14. $H_{\varepsilon}^{+}, H_{\varepsilon}^{-}$and $H_{\varepsilon}^{\infty}$ are pairwise recursively inseparable.
Proof.

- $\left(H_{\varepsilon}^{+}, H_{\varepsilon}^{\infty}\right)$ : We show that every set $C$ with $H_{\varepsilon}^{+} \subseteq C$ and $H_{\varepsilon}^{\infty} \cap C=$ $\varnothing$ is undecidable by reducing the halting problem $H_{\varepsilon}$ to $C$. Define the function $\rho(M) \mapsto \rho\left(M^{\prime}\right)$ as follows. From a given code $\rho(M)$ construct the code of a TM $M^{\prime}$ that simulates $M$ and simultaneously counts the number of computation steps since the start. If $M$ halts (accepting or rejecting), $M^{\prime}$ accepts.

It is clear that the reduction function is computable. If $M$ halts on $\varepsilon$ then $M^{\prime}$ halts on $\varepsilon$ as well and accepts, so $\rho\left(M^{\prime}\right) \in H_{\varepsilon}^{+} \subseteq C$. If $M$ does not halt on $\varepsilon$ then $M^{\prime}$ does not halt either, so $\rho\left(M^{\prime}\right) \in H_{\varepsilon}^{\infty}$ and as $H_{\varepsilon}^{\infty} \cap C=\varnothing$, we have $\rho\left(M^{\prime}\right) \notin C$.

- The statement for $H_{\varepsilon}^{-}$and $H_{\varepsilon}^{\infty}$ is proven analogously.
- $\left(H_{\varepsilon}^{-}, H_{\varepsilon}^{+}\right)$: Show that $\left(H_{0}^{-}, H_{0}^{+}\right) \leq\left(H_{\varepsilon}^{-}, H_{\varepsilon}^{+}\right)$and that $\left(H_{0}^{-}, H_{0}^{+}\right)$ are recursively inseparable.
- $\left(H_{0}^{-}, H_{0}^{+}\right) \leq\left(H_{\varepsilon}^{-}, H_{\varepsilon}^{+}\right):$

For a given input TM $M$ construct a TM $M^{\prime}$ that ignores its own input and simulates $M$ on $\rho(M)$. Obviously, $M^{\prime}$ can be constructed effectively, say by a computable function $h$. Now $h(M)$ accepts $\varepsilon$ iff $M$ accepts $\rho(M)$ and $h(M)$ rejects $\varepsilon$ iff $M$ rejects $\rho(M)$.

- $\left(H_{0}^{-}, H_{0}^{+}\right)$recursively inseparable:

Assume there exists a decidable $C$ with $H_{0}^{-} \subseteq C$ and $H_{0}^{+} \subseteq \bar{C}$. Consider a machine $M_{0}$ that decides $C$. There are two cases:
(1) $M_{0}$ accepts $\rho\left(M_{0}\right)$. Then $\rho\left(M_{0}\right) \in C$ by definition of $M_{0}$. Then $\rho\left(M_{0}\right) \notin H_{0}^{+}$by definition of $C$. On the other hand, if $M_{0}$ accepts $\rho\left(M_{0}\right)$ then $\rho\left(M_{0}\right) \in H_{0}^{+}$(by definition of $H_{0}^{+}$), a contradiction.
(2) $M_{0}$ rejects $\rho\left(M_{0}\right)$. Then $\rho\left(M_{0}\right) \notin C$ by definition of $M_{0}$. Then $\rho\left(M_{0}\right) \notin H_{0}^{-}$by definition of $C$. On the other hand, if $M_{0}$ rejects $\rho\left(M_{0}\right)$ then $\rho\left(M_{0}\right) \in H_{0}^{-}$(by definition of $H_{0}^{-}$), a contradiction.

### 1.2 Trakhtenbrot's Theorem

In the following, we consider FO, more precisely first-order logic with equality. We restrict ourselves to a countable signature

$$
\tau_{\infty}:=\left\{R_{j}^{i}: i, j \in \mathbb{N}\right\} \cup\left\{f_{j}^{i}: i, j \in \mathbb{N}\right\}
$$

where $R_{j}^{i}$ stands for a relation symbol of arity $i$ and $f_{j}^{i}$ stands for a function symbol of arity $i$.

We encode formulae over a fixed alphabet

$$
\Gamma:=\{R, f, x, 0,1,[,]\} \cup\{=, \neg, \wedge, \vee, \rightarrow, \leftrightarrow, \exists, \forall \cdot(,)\},
$$

and uniquely encode the relational and functional symbols

| relation symbols: | $R_{j}^{i}$ | $\longmapsto$ | $R[$ bin $i][$ bin $j]$ |
| :--- | :---: | :--- | :--- |
| functional symbols: | $f_{j}^{i}$ | $\longmapsto$ | $f[\operatorname{bin} i][$ bin $j]$ |
| variables: | $x_{j}$ | $\longmapsto$ | $x[\operatorname{bin} j]$. |

Thus, every formula $\varphi \in \mathrm{FO}$ is a word in $\Gamma^{*}$.
Let $X \subseteq$ FO be a class of formulae. We analyse the following decision problems:

$$
\begin{aligned}
& \operatorname{Sat}(X):=\{\psi \in X: \psi \text { has a model }\} \\
& \text { Fin-sat }(X):=\{\psi \in X: \psi \text { has a finite model }\} \\
& \operatorname{Val}(X):=\{\psi \in X: \psi \text { is valid }\} \\
& \operatorname{Non-sat}(X):=X \backslash \operatorname{Sat}(X) \\
& \operatorname{Inf-axioms}(X):=\operatorname{Sat}(X) \backslash \text { Fin-sat }(X) \\
&=\{\psi \in X: \psi \text { is an infinity axiom, i.e. } \psi \text { has a } \\
&\text { model but no finite model }\} .
\end{aligned}
$$

Theorem 1.15. Let $X \subseteq$ FO be decidable. Then
(1) $\operatorname{Val}(X)$ is r.e.
(2) Non-sat (X) is r.e
(3) $\operatorname{Sat}(X)$ is co-r.e.
(4) Fin-sat $(X)$ is r.e.
(5) Inf-axioms ( $X$ ) is co-r.e.

Proof. (1) $\varphi$ is valid $\Leftrightarrow \vdash \varphi$ (Completeness Theorem). Thus we can systematically enumerate all proofs and halt if a proof for $\varphi$ is listed.
(2) $\varphi$ valid $\Leftrightarrow \neg \varphi$ is not satisfiable.
(3) Follows from Item (2).
(4) Systematically generate all finite models and halt if a model of $\varphi$ is found.
(5) $\mathrm{FO} \backslash \operatorname{Inf}$-axioms $(X)=\operatorname{Non-sat}(X) \cup \operatorname{Fin}$-sat $(X)$ is r.e.

Definition 1.16. A class $X \subseteq$ FO has the finite model property (FMP) if every satisfiable $\varphi \in X$ has a finite model, i.e. if $\operatorname{Sat}(X)=\operatorname{Fin}$-sat $(X)$.

Theorem 1.17. Suppose that $X \subseteq F O$ is decidable and that $X$ has the FMP. Then $\operatorname{Sat}(X)$ is decidable.
$\operatorname{Proof}$. $\operatorname{Sat}(X)$ is co-r.e. and since $\operatorname{Sat}(X)=\operatorname{Fin}-\operatorname{sat}(X)$ and $\operatorname{Fin}-\operatorname{sat}(X)$ is r.e. also $\operatorname{Sat}(X)$ is r.e. Thus $\operatorname{Sat}(X)$ is decidable.

In this case also Fin-sat $(X), \operatorname{Non-sat}(X), \operatorname{Val}(X)$ are decidable and of course $\operatorname{Inf}$-axioms $(X)=\varnothing$ is decidable.

Theorem 1.18 (Trakhtenbrot). There is a finite vocabulary $\tau \subseteq \tau_{\infty}$ such that $\operatorname{Fin}-\operatorname{sat}(\operatorname{FO}(\tau)), \operatorname{Non-sat}(\mathrm{FO}(\tau))$ and $\operatorname{Inf}-\operatorname{axioms}(\mathrm{FO}(\tau))$ are pairwise recursively inseparable and therefore undecidable.

The proof of Trakhtenbrot's theorem introduces a proof strategy that can be applied in many other undecidability proofs. (Do not focus on the technicalities but on the general idea to construct the reduction formulae.)

Proof. Let $M$ be a deterministic Turing acceptor. We show that there is an effective reduction $\rho(M) \mapsto \psi_{M}$ such that
(1) $M$ accepts $\varepsilon \Longrightarrow \psi_{M}$ has a finite model.
(2) $M$ rejects $\varepsilon \Longrightarrow \psi_{M}$ is unsatisfiable.
(3) The computation of $M$ on $\varepsilon$ is infinite and non-periodic $\Longrightarrow \psi_{M}$ is an infinity axiom.

Then the theorem follows by Lemma 1.13.
Let $M$ be a Turing acceptor with states $Q=\left\{q_{0}, \ldots, q_{r}\right\}$, initial state $q_{0}$, alphabet $\Sigma=\left\{a_{0}, \ldots, a_{s}\right\}$ (where $a_{0}=\square$ ), final states $F=F^{+} \cup F^{-}$ and transition function $\delta$.
$\psi_{M}$ is defined over the vocabulary $\tau=\{0, f, q, p, w\}$ where 0 is a constant, $f, q, p$ are unary functions and $w$ is a binary function. Define the term $k$ as $f^{k} 0$.

By constructing a formula we intend to have a model $\mathfrak{A}_{M}=$ $(A, 0, f, q, p, w)$ describing a run of $M$ on the input $\varepsilon$ where

- universe $A=\{0,1,2, \ldots, n\}$ or $A=\mathbb{N}$;
- $f(t)=t+1$ if $t+1 \in A$ and $f(t)=t$, if $t$ is the last element of $A$;
- $q(t)=i$ iff $M$ is at time $t$ in state $q_{i}$;
- $p(t)$ is the head position of $M$ at time $t$;
- $w(s, t)=i$ iff symbol $a_{i}$ is at time $t$ on tape-cell $s$.

Note that we cannot enforce this model, but if $\psi_{M}$ is satisfiable this one will be among its models.

$$
\psi_{M}:=\text { START } \wedge \text { COMPUTE } \wedge \mathrm{END}
$$

$$
\text { START }:=(q 0=0 \wedge p 0=0 \wedge \forall x w(x, 0)=0)
$$

[Enforces input configuration on $\varepsilon$ at time 0]

$$
\text { COMPUTE }:=\text { NOCHANGE } \wedge \text { CHANGE }
$$

$$
\text { NOCHANGE }:=\forall x \forall y(p y \neq x \rightarrow w(x, f y)=w(x, y))
$$

[content of currently not visited tape cells does not change]

$$
\mathrm{CHANGE}:=\bigwedge_{\delta:\left(q_{i}, a_{j}\right) \mapsto\left(q_{k}, a_{\ell}, m\right)} \forall y\left(\alpha_{i, j} \rightarrow \beta_{k, \ell, m}\right)
$$

where

$$
\begin{aligned}
& \alpha_{i j}:=(q y=i \wedge w(p y, y)=j) \\
& {\left[M \text { is at time } y \text { in state } q_{i} \text { and reads the symbol } a_{j}\right] } \\
& \beta_{k, \ell, m}:=\left(q f y=k \wedge w(p y, f y)=\ell \wedge \mathrm{MOVE}_{m}\right)
\end{aligned}
$$

and

$$
\begin{aligned}
\operatorname{MOVE}_{m} & := \begin{cases}p f y=p y & \text { if } m=0 \\
p f y=f p y & \text { if } m=1 \\
\exists z(f z=p y \wedge p f y=z) & \text { if } m=-1 . \\
\mathrm{END} & :=\bigwedge_{\substack{\delta\left(q_{i}, a_{j}\right) \text { undef. } \\
q_{i} \notin F^{+}}} \forall y \neg \alpha_{i j}\end{cases}
\end{aligned}
$$

[The only way the computation ends is in an accepting state]

## Remark 1.19.

- $\rho(M) \mapsto \psi_{M}$ is an effective construction.
- If $M$ accepts $\varepsilon$, the intended model is finite and is indeed a model $\mathfrak{A}_{M}=\psi_{M}$, thus $\psi_{M} \in \operatorname{Fin}-\operatorname{sat}(F O(\tau))$.
- If the computation of $M$ on $\varepsilon$ is infinite, the intended model is infinite and $\mathfrak{A}_{M}=\psi_{M}$.

It remains to show that if $M$ rejects $\varepsilon$, then $\psi_{M}$ is unsatisfiable, and if the computation of $M$ on $\varepsilon$ is infinite and aperiodic, then $\psi_{M}$ is an infinity axiom.

Suppose $\mathfrak{B}=(B, 0, f, q, p, w) \models \psi_{M}$.
Definition 1.20. $\mathfrak{B}$ enforces at time $t$ the configuration $\left(q_{i}, j, w\right)$ with $w=a_{i_{0}} \ldots a_{i_{m}} \in \Sigma^{*}$ if
(1) $\mathfrak{B} \mid=q t=\boldsymbol{i}$
(2) $\mathfrak{B} \mid=p t=j$,
(3) for all $k \leq m, \mathfrak{B} \models w(\boldsymbol{k}, \boldsymbol{t})=\boldsymbol{i}_{\boldsymbol{k}}$ and for all $k>m, \mathfrak{B} \models w(\boldsymbol{k}, \boldsymbol{t})=0$.

Since $\mathfrak{B} \models \psi_{M}$, the following holds:

- $\mathfrak{B}$ enforces $C_{0}=\left(q_{0}, 0, \varepsilon\right)$ at time 0 (since $\mathfrak{B} \models$ START.)
- If $\mathfrak{B}$ enforces at time $t$ a non-final configuration $C_{t}$, then $\mathfrak{B}$ enforces the configuration $C_{t+1}=\operatorname{Next}\left(C_{\mathrm{t}}\right)$ at time $t+1$.
- Especially, the computation of $M$ cannot reach a rejecting configuration. It follows that if $M$ rejects $\varepsilon$, then $\psi_{M}$ is unsatisfiable.

Consider an infinite and aperiodic computation of $M$, and assume $\mathfrak{B} \models \psi_{M}$ is finite. Since $\mathfrak{B}$ is finite, it enforces a periodic computation in contradiction to the assumption that the computation of $M$ is aperiodic.

$$
C_{0} \vdash \ldots \vdash \underbrace{C_{r}} \vdash \ldots \vdash C_{t-1}
$$

We have shown:

- If $M$ accepts $\varepsilon$, then $\psi_{M}$ has a finite model.
- If $M$ rejects $\varepsilon$, then $\psi_{M}$ is unsatisfiable.
- If the computation of $M$ is infinite and aperiodic, then $\psi_{M}$ is an infinity axiom.

We now know that the sets of all finitely satisfiable, all unsatisfiable and all only infinitely satisfiable formulae are undecidable for $\mathrm{FO}(\tau)$ where $\tau$ consists of only three unary functions and one binary function. This raises a number of questions.
(1) For which other vocabularies $\sigma$ do we have similar undecidability results for $\mathrm{FO}(\sigma)$ ?
(2) For which $\sigma$ is satisfiability of $\operatorname{FO}(\sigma)$ decidable?
(3) Is there a complete classification? In this case, we want to find minimal vocabularies $\sigma$ such that the above problems are undecidable, i.e. vocabularies such that any further restriction yields a class of formulae for which satisfiability is decidable.

We first define what it means that a fragment of FO is as hard for satisfiability as the whole FO.
Definition 1.21. $X \subseteq F O$ is a reduction class if there exists a computable function $f: \mathrm{FO} \rightarrow X$ such that $\psi \in \operatorname{Sat}(\mathrm{FO}) \Leftrightarrow f(\psi) \in \operatorname{Sat}(X)$.

Let $X, Y \subseteq$ FO. A conservative reduction of $X$ to $Y$ is a computable function $f: X \rightarrow Y$ with

- $\psi \in \operatorname{Sat}(X) \Leftrightarrow f(\psi) \in \operatorname{Sat}(Y)$, and
- $\psi \in \operatorname{Fin}-\operatorname{sat}(X) \Leftrightarrow f(\psi) \in \operatorname{Fin-sat}(Y)$.
$X$ is a conservative reduction class if there exists a conservative reduction of FO to $X$.

Corollary 1.22. Let $X$ be a conservative reduction class. Then Fin-sat $(X), \operatorname{Inf-axioms}(X)$ and Non-sat $(X)$ are pairwise recursively inseparable, and thus Fin-sat $(X), \operatorname{Sat}(X), \operatorname{Val}(X), \operatorname{Non-sat}(X), \operatorname{Inf}-\operatorname{axioms}(X)$ are undecidable.

Proof. A conservative reduction from FO to X yields a uniform reduction from $\operatorname{Fin}-\operatorname{sat}(\mathrm{FO}), \operatorname{Inf}-\operatorname{axioms}(\mathrm{FO})$ and $\operatorname{Non-sat}(\mathrm{FO})$ to Fin-sat(X), $\operatorname{Inf}$-axioms $(X)$ and $\operatorname{Non-sat(X),~respectively.~}$
Q.E.D.

We now observe that we can indeed give a complete classification of signatures $\sigma$ such that $\mathrm{FO}(\sigma)$ is decidable.
Theorem 1.23. If $\sigma \subseteq\left\{P_{0}, P_{1}, \ldots\right\} \cup\{f\}$ consists of at most one unary function $f$ and an arbitrary number of monadic relations $P_{0}, P_{1}, \ldots$, then $\operatorname{Sat}(\mathrm{FO}(\sigma))$ is decidable. In all other cases, $\operatorname{Sat}(\mathrm{FO}(\sigma))$, Inf-axioms $(\mathrm{FO}(\sigma))$ and $\operatorname{Non-sat(~} \mathrm{FO}(\sigma))$ are pairwise recursively inseparable, and $\mathrm{FO}(\sigma)$ is a conservative reduction class.

A full proof of this classification theorem is rather difficult. In particular, the decidability of the monadic theory of one unary function, which implies the decidability part, is a difficult theorem due to Rabin. On the other side, one has to show that Trakhtenbrot's theorem applies to the vocabularies
$\tau_{1}=\{E\}$ where $E$ is a binary relation,
$\tau_{2}=\{f, g\}$ where $f, g$ are unary functions,
$\tau_{3}=\{F\}$ where $F$ is a binary function,
and hence to all extensions of $\tau_{1}, \tau_{2}, \tau_{3}$.
Of course, we may also look at other syntactic restrictions besides restricting the vocabulary. One possibility is to restrict the number of variables. This is only interesting for relational formulae. If we have functions, satisfiability is undecidable even for formulae with only one variable as we shall see.

Define $\mathrm{FO}^{k}$ as first-order logic with relational symbols only and a fixed amount of $k$ variables, say $x_{1}, \ldots, x_{k}$.

## Theorem 1.24.

- $\mathrm{FO}^{2}$ has the finite model property and is decidable (see Chapter 2).
- $\mathrm{FO}^{3}$ is a conservative reduction class.

Another possibility is to restrict the structure of quantifier prefixes.
Definition 1.25 (Prefix-Vocabulary Classes). A string in $\{\forall, \exists\}^{*}$ is called prefix, and an arity sequence is a sequence assigning all positive integers values in $\mathbb{N} \cup\{\omega\}$.

For any set of prefixes $\Pi$ and any arity sequences $p$ and $f,[\Pi, p, f]$ and $[\Pi, p, f]_{=}$denote the collection of all formulae $\varphi \in$ FO in prenex normal form without equality and with equality, respectively, such that

- the prefix of $\varphi$ belongs to $\Pi$,
- the number of $n$-ary predicate symbols in $\varphi$ is at most $p(n)$ and
- the number of $n$-ary function symbols in $\varphi$ is at most $f(n)$.
- Except for the logical constants true and false, $\varphi$ has no nullary predicate symbols, no nullary function symbols and no free variables.

The prefix set containing all prefixes and the arity sequence that assigns $\omega$ to each $n$ will be denoted all.

We write arity sequences as tuples, e.g., $(2,1, \omega)$, ( 0 ) to express that two predicate symbols of arity 1 , one of arity 2 , unboundedly many of arity 3 and no other predicate or function symbols are allowed.

Theorem 1.26 (Gurevich). Let $X$ be a prefix class, $p, q$ two arity sequences and $X=[\Pi, p, q]_{=}$.

- $X$ is a conservative reduction class if it contains any of
(1) $[\forall,(0),(2)]=$
(2) $[\forall,(0),(0,1)]=$
(3) $\left[\forall^{2} \exists,(\omega, 1),(0)\right]=$
(4) $\left[\exists^{*} \forall^{2} \exists,(0,1),(0)\right]=$
(5) $\left[\forall^{2} \exists^{*},(0,1),(0)\right]=$
- If $X$ is contained in one of the following classes, then $\operatorname{Sat}(X)$ and Inf-axioms $(X)$ are decidable
(6) $\left[\exists^{*} \forall^{*}\right.$, all,$\left.(0)\right]=$
(7) $\left[\exists^{*}\right.$, all, all $]=$
(8) $[$ all, $(\omega),(1)]=$
(9) $\left[\exists^{*} \forall \exists *, \text { all },(1)\right]_{=}$.

This gives a complete classification.

### 1.3 Domino problems

Domino problems are a simple and yet general tool for proving undecidability without talking about Turing machines

The informal idea is the following: a domino (type) is an oriented square with unit length and coloured edges. We consider the following decision problem.

Given: a finite set of domino types (infinite supply of each).
Question: does there exist a tiling of $\mathbb{N} \times \mathbb{N}$ such that adjacent edges have the same colour?
The undecidability of the stated problem is established by encoding computations of Turing machines in an appropriate way. A row of the tiling represents a configuration of a Turing machine.

Definition 1.27. A domino system is a structure $\mathcal{D}=(D, H, V)$ with

- a finite set $D$,
- horizontal and vertical compatibility relations $H, V \subseteq D \times D$.

The meaning of $H$ and $V$ is that

- $\left(d, d^{\prime}\right) \in H$ if the right colour of $d$ is equal to the left colour of $d^{\prime}$,
- $\left(d, d^{\prime}\right) \in V$ if the top colour of $d$ is equal to the bottom colour of $d^{\prime}$ (see Figure 1.1).

A tiling of $\mathbb{N} \times \mathbb{N}$ by $\mathcal{D}$ is a function $\sigma: \mathbb{N} \times \mathbb{N} \rightarrow D$ such that for all $x, y \in \mathbb{N}$

- $(\sigma(x, y), \sigma(x+1, y)) \in H$ and
- $(\sigma(x, y), \sigma(x, y+1)) \in V$.

A periodic tiling of $\mathbb{N} \times \mathbb{N}$ by $\mathcal{D}$ is a tiling $\sigma$ for which two integers $h, v \in \mathbb{N}$ exist such that for all $x, y \in \mathbb{N}$ it holds $\sigma(x, y)=\sigma(x+h, y)=$ $\sigma(x, y+v)$. The decision problem DOMINO is described as

DOMINO $:=\{\mathcal{D}:$ there exists a tiling of $\mathbb{N} \times \mathbb{N}$ by $\mathcal{D}\}$


Figure 1.1. Domino adjacency condition

An important variant is the origin constrained tiling.
Definition 1.28. An origin constrained domino system is a system $\left(\mathcal{D}, D_{0}\right)$ with $D_{0} \subseteq D$. A tiling with origin constraint $D_{0}$ is a tiling $\sigma$ such that $\sigma(0,0) \in D_{0}$. The corresponding decision problem is

$$
\begin{array}{r}
\text { CORNER-DOMINO: }=\left\{\left(\mathcal{D}, D_{0}\right): \text { there exists a tiling of } \mathbb{N} \times \mathbb{N}\right. \\
\text { with origin constraint } \left.D_{0}\right\} .
\end{array}
$$

Theorem 1.29 (Wang, Büchi). CORNER-DOMINO is undecidable.

Proof. We reduce $H_{\varepsilon}^{\omega}=\{\rho(M)$ : the computation of $M$ on $\varepsilon$ is infinite $\}$, which is co-r.e., to CORNER-DOMINO.

Consider a 1-tape $\operatorname{TM} M=\left(Q, \Sigma, q_{0}, \delta, F\right)$, and construct $\left(\mathcal{D}, D_{0}\right)$ such that the computation of $M$ on $\varepsilon$ is infinite if and only if there exists a tiling of $\mathbb{N} \times \mathbb{N}$ by $\mathcal{D}$ with origin constraint $D_{0}$.

Assume w.l.o.g. that $M$ never moves off-tape to the left, i.e. in configurations $(q, 0, w)$ it is never the case that $\delta\left(q, w_{0}\right)=\left(q^{\prime}, a,-1\right)$.
$D$ consists of the following domino types.

For each $a \in \Sigma$

For each $(q, a) \in Q \times \Sigma$ with
$\delta(q, a)=\left(q^{\prime}, a^{\prime}, 0\right)$

|  | $a$ |  |
| :--- | :--- | :--- |
|  | $\leftrightarrow$ |  |
|  |  | $\leftrightarrow$ |
|  |  |  |
|  |  |  |
|  |  |  |

$$
\leftrightarrow q_{(q, a)}^{\left(q^{\prime}, a^{\prime}\right)} \leftrightarrow
$$

For each $(q, a) \in Q \times \Sigma$ with $\delta(q, a)=\left(q^{\prime}, a^{\prime}, 1\right)$, for each $b \in \Sigma$


For each $(q, a) \in Q \times \Sigma$ with $\delta(q, a)=\left(q^{\prime}, a^{\prime},-1\right)$ for each $b \in \Sigma$

Additionally there exist dominoes


The origin constraint $D_{0}$ consists of


Note that $\left(\mathcal{D}, D_{0}\right)$ can be constructed effectively from $M$.
There is precisely one way of tiling the first row:

$\sigma(0,0)$
$\sigma(0, i)$
for all $i>0$

Assume the first $j$ rows have been tiled correctly. Then the top edge of row $j$ reads

$$
w_{0} \ldots w_{i-1}\left(q, w_{i}\right) w_{i+1} \ldots
$$

for $C_{j}=\left(q, i, w_{0}, w_{1}, \ldots\right)$, the $j$ th configuration of $M$ on $\varepsilon$.
This tiling can be extended to a tiling of row $j+1$ if and only if there exists $C_{j+1}=\operatorname{Next}\left(C_{j}\right)$.

Conclusion: The computation of $M$ on $\varepsilon$ is infinite if and only if there exists a tiling of $\mathbb{N} \times \mathbb{N}$ by $\left(\mathcal{D}, D_{0}\right)$.
Q.E.D.

Stronger forms of this result are the following
Theorem 1.30 (Berger, Robinson). DOMINO (without origin constraint) is co-r.e. and undecidable.

Theorem 1.31. The problem of tiling $\mathbb{Z} \times \mathbb{Z}$ is reducible to the problem of tiling $\mathbb{N} \times \mathbb{N}$. (Proof via König's Lemma).

Theorem 1.32. The set of domino systems admitting a periodic tiling of $\mathbb{N} \times \mathbb{N}$, those that admit no tiling of $\mathbb{N} \times \mathbb{N}$ and those that admit a tiling but not a periodic one are pairwise recursively inseparable.

Definition 1.33. A computable function $f$ is a reduction from domino systems to $X$ if, for all domino systems $\mathcal{D}, f(\mathcal{D})=\varphi_{\mathcal{D}}$ is in $X$ and the following holds:

- $\mathcal{D}$ admits a periodic tiling of $\mathbb{N} \times \mathbb{N} \Rightarrow \psi_{\mathcal{D}}$ has a finite model
- $\mathcal{D}$ admits no tiling of $\mathbb{N} \times \mathbb{N} \Rightarrow \psi_{\mathcal{D}}$ is unsatisfiable
- $\mathcal{D}$ admits a tiling of $\mathbb{N} \times \mathbb{N}$ but no periodic one $\Rightarrow \psi_{\mathcal{D}}$ is an infinity axiom.

Remark 1.34. Let $X \in$ FO. If there exists a reduction from domino systems to $X$ then $X$ is a conservative reduction class.

Proof. Since Fin-sat(FO) and Non-sat(FO) are recursively enumerable and Inf-axioms(FO) is co-recursively enumerable, we can associate with every first-order formula $\psi$ a Turing machine $M$ such that

- $\psi \in \operatorname{Fin-sat}(\mathrm{FO}) \Rightarrow \rho(M) \in H_{\varepsilon}^{+}$,
- $\psi \in \operatorname{Non-sat}(\mathrm{FO}) \Rightarrow \rho(M) \in H_{\varepsilon}^{-}$,
- $\psi \in \operatorname{Inf-axioms}(\mathrm{FO}) \Rightarrow \rho(M) \in H_{\varepsilon}^{\infty}$.

The proof of 1.32 reduces the halting problems $H_{\varepsilon}^{+}, H_{\varepsilon}^{-}, H_{\varepsilon}^{\infty}$, to the domino problems. There exists a recursive function that associates with every TM $M$ a domino system $\mathcal{D}$ satisfying

- If $M \in H_{\varepsilon}^{+}$then $\mathcal{D}$ admits a periodic tiling of $\mathbb{N} \times \mathbb{N}$.
- If $M \in H_{\varepsilon}^{-}$then $\mathcal{D}$ admits no tiling of $\mathbb{N} \times \mathbb{N}$.
- If $M \in H_{\varepsilon}^{\infty}$ then $\mathcal{D}$ admits a tiling of $\mathbb{N} \times \mathbb{N}$ but no periodic one.

Finally, according to to the assumption, there is a reduction $\mathcal{D} \mapsto$ $\varphi_{\mathcal{D}}$ from domino systems to $X$ Thus, the domino method yields a conservative reduction from FO to $X$.
Q.E.D.

### 1.4 Applications of the domino method

We now apply the domino method to obtain several reduction classes.
Theorem 1.35. $[\forall \exists \forall,(0, \omega),(0)]$ is a conservative reduction class.
Proof. Due to Remark 1.34 it suffices to give a reduction from domino systems to $X$, i.e. find a mapping $\mathcal{D} \mapsto \psi_{\mathcal{D}}$ over a vocabulary consisting of binary relation symbols $\left(P_{d}\right)_{d \in D}$ such that
(1) $\mathcal{D}$ admits a periodic tiling of $\mathbb{N} \times \mathbb{N} \Rightarrow \psi_{\mathcal{D}}$ has a finite model
(2) $\mathcal{D}$ admits no tiling of $\mathbb{N} \times \mathbb{N} \Rightarrow \psi_{\mathcal{D}}$ is unsatisfiable
(3) $\mathcal{D}$ admits a tiling of $\mathbb{N} \times \mathbb{N}$ but no periodic one $\Rightarrow \psi_{\mathcal{D}}$ is an infinity axiom

The intended model is $\mathbb{N}$ with intended interpretation of $P_{d}=$ $\{(i, j) \in \mathbb{N} \times \mathbb{N}: \tau(i, j)=d\}$ for all $d \in D$. We define $\psi_{\mathcal{D}}$ by

$$
\begin{aligned}
\psi_{\mathcal{D}}:=\forall x \exists y \forall z & \left(\bigwedge_{d \neq d^{\prime}} P_{d} x z \rightarrow \neg P_{d^{\prime}} x z\right. \\
& \left.\wedge \bigvee_{\left(d, d^{\prime}\right) \in H}\left(P_{d} x z \wedge P_{d^{\prime}} y z\right) \wedge \bigvee_{\left(d, d^{\prime}\right) \in V}\left(P_{d} z x \wedge P_{d^{\prime}} z y\right)\right) .
\end{aligned}
$$

Obviously $\psi_{\mathcal{D}}$ is of the desired format, i.e. $\psi_{\mathcal{D}} \in[\forall \exists \forall,(0, \omega),(0)]$.
(1) If $\mathcal{D}$ admits a periodic tiling of $\mathbb{N} \times \mathbb{N}$, then $\psi_{\mathcal{D}}$ has a finite model Let $\tau: \mathbb{N} \times \mathbb{N} \rightarrow D$ be a periodic tiling such that for some $h, v \in \mathbb{N}$ $\tau(x, y)=\tau(x+h, y)=\tau(x, y+v)$ for all $x, y$. Let $t:=l c m(h, v)$ be the least common multiple of $h$ and $v$. Then $\tau$ induces a tiling

$$
\tau: \mathbb{Z} / t \mathbb{Z} \times \mathbb{Z} / t \mathbb{Z} \rightarrow D
$$

with $\tau^{\prime}(x, y)=\tau(x(\bmod t), y(\bmod t))$.
Thus, $\mathfrak{A}=\left(\mathbb{Z} / t \mathbb{Z},\left(P_{d}\right)_{d \in D}\right)$ with $P_{d}=\left\{(i, j): \tau^{\prime}(i, j)=d\right\}$ is a finite model (for $x$ in $\psi_{\mathcal{D}}$ choose $y:=x+1(\bmod t)$ in $\psi_{\mathcal{D}}$.)
(2) If $\psi_{\mathcal{D}}$ has a model, then $\mathcal{D}$ admits a tiling.
(3) We want to show: if $\psi_{\mathcal{D}}$ has a finite model, then $\mathcal{D}$ admits a periodic tiling. (In the case that $\psi_{\mathcal{D}}$ is unsatisfiable, we show with the same arguments as in (1) that if $\mathcal{D}$ admits a tiling of $\mathbb{N} \times \mathbb{N}$, then $\psi_{\mathcal{D}}$ has a model $\mathfrak{A}=\left(\mathbb{N},\left(P_{d}\right)_{d \in D}\right)$.)

Let now $\psi_{\mathcal{D}}$ have a finite model. To show that if $\psi_{\mathcal{D}}$ has a (finite) model, then $\mathcal{D}$ admits a (periodic) tiling we consider the Skolem normal form $\varphi_{\mathcal{D}}$ of $\psi_{\mathcal{D}}$ :

$$
\begin{aligned}
\varphi_{\mathcal{D}}:=\forall x \forall z & \left(\bigwedge_{d \neq d^{\prime}} P_{d} x z \rightarrow \neg P_{d^{\prime}} x z\right. \\
& \wedge \bigvee_{\left(d, d^{\prime}\right) \in H}\left(P_{d} x z \wedge P_{d^{\prime}} f x z\right) \wedge \bigvee_{\left(d, d^{\prime}\right) \in V}\left(P_{d} z x \wedge P_{d^{\prime}} z f x\right)
\end{aligned}
$$

- Suppose $\mathfrak{B}=\left(B, f,\left(P_{d}\right)_{d \in D}\right) \models \varphi_{\mathcal{D}}$. Define a tiling $\tau: \mathbb{N} \times \mathbb{N} \rightarrow$ $D$ as follows: choose $b \in B$, and set $\tau(i, j):=d$ for the unique
$d \in D$ such that $\mathfrak{B} \models P_{d}\left(f^{i} b, f^{j} b\right)$ for all $i, j \in \mathbb{N}$. Since $\mathfrak{B} \models \varphi_{\mathcal{D}}, \tau$ is a correct tiling.
- Suppose that $\mathfrak{B} \models \varphi_{\mathcal{D}}$ is finite:


Choose $b \in B$ such that, for some $t \geq 1, f^{t} b=b$. Then the defined tiling $\tau$ is periodic.
Q.E.D.

Corollary 1.36. $F O^{3}$ is a conservative reduction class.
Later we show that $F O^{2}$ has the FMP.
Consider sets of formulae $X \subseteq$ FO over functional vocabularies. $\mathrm{FO}(\tau)$ is a conservative reduction class if $\tau$ contains

- two unary functions or
- one binary function.

This is even true for sentences of the form $\forall x \varphi$ where $\varphi$ is quantifierfree.

Theorem 1.37. $[\forall,(0),(2)]=$ and $[\forall,(0),(0,1)]=$ are conservative reduction classes.

Proof. We apply the domino method for formulae $\forall x \varphi$ where $\varphi$ is quantifier-free with any number of unary functions, and then apply a reduction/interpretation to reduce this to two unary/one binary function/s.

Define a mapping $\mathcal{D}=(D, H, V) \mapsto \psi_{\mathcal{D}}$ where $\psi_{\mathcal{D}}$ is a formula over the vocabulary $\left\{f, g,\left(h_{d}\right)_{d \in D}\right\}$ where all function symbols are unary. The intended model is $\mathbb{N} \times \mathbb{N}$ with successor functions $f$ and $g$. The subformula $\forall x(f g x=g f x)$ ensures that the models of $\psi_{\mathcal{D}}$ contain a two-dimensional grid. The fact that a position $x$ is tiled by $d \in D$ is
expressed by requiring that $h_{d} x=x$, i.e. that $x$ is a fixed point of $h_{d}$. Now define

$$
\begin{aligned}
\psi_{\mathcal{D}}:=\forall x(f g x=g f x & \wedge \bigwedge_{d \neq d^{\prime}}\left(h_{d} x=x \rightarrow h_{d^{\prime}} x \neq x\right) \\
& \wedge \bigvee_{\left(d, d^{\prime}\right) \in H}\left(h_{d} x=x \wedge h_{d^{\prime}} f x=f x\right) \\
& \left.\wedge \bigvee_{\left(d, d^{\prime}\right) \in V}\left(h_{d} x=x \wedge h_{d^{\prime}} g x=g x\right)\right) .
\end{aligned}
$$

We claim that there exists a tiling $\sigma: \mathbb{N} \times \mathbb{N} \rightarrow \mathcal{D}$ if and only if $\psi_{\mathcal{D}}$ is satisfiable.
$" \Rightarrow "$ Assume $\sigma$ is a correct tiling. Construct the (intended) model $\mathfrak{A}=\left(\mathbb{N} \times \mathbb{N}, f, g,\left(h_{d}\right)_{d \in \mathcal{D}}\right)$ with
$-f(i, j)=(i+1, j)$,

$$
\begin{aligned}
& -g(i, j)=(i, j+1) \\
& -h_{d}(i, j) \begin{cases}=(i, j) & \text { if } \sigma(i, j)=d \\
\neq(i, j) & \text { otherwise }\end{cases}
\end{aligned}
$$

Clearly $\mathfrak{A}=\psi_{\mathcal{D}}$.
$" \Leftarrow "$ Consider $\mathfrak{B}=\left(B, f, g,\left(h_{d}\right)_{d \in \mathcal{D}}\right) \models \psi_{\mathcal{D}}$.
Choose an arbitrary $b \in B$ and define

$$
\sigma: \mathbb{N} \times \mathbb{N} \rightarrow \mathcal{D}: \sigma(i, j):=d \text { iff } \mathfrak{B} \models h_{d} f^{i} g^{j} b=f^{i} g^{j} b
$$

Note that every position is in exactly one of the $h_{d}$. Then $\sigma$ is a correct tiling. If $\mathfrak{B}$ is finite, then $\sigma$ is periodic, and thus the reduction is conservative.
We now show that we can sharpen the results, i.e. show that two unary function symbols are sufficient

Consider $\forall x \varphi \in[\forall,(0),(\omega)]=$ with monadic function symbols $f_{1}, \ldots, f_{m}$. Transform $\varphi$ into $\tilde{\varphi}:=\varphi\left[x / h x, f_{i} / h g^{i}\right]$ where $h, g$ are fresh unary function symbols. This procedure transforms formulae over the vocabulary $\left\{f_{1}, \ldots, f_{m}\right\}$ into formulae over the vocabulary $\{h, g\}$. The idea is to replace an application of $f_{i}$ by $i$ applications of $g$. The second function $h$ takes care of unwanted equalities.


Claim: $\forall x \varphi$ is (finitely) satisfiable $\Leftrightarrow \forall x \tilde{\varphi}$ is (finitely) satisfiable.
$" \Leftarrow "$ Let $\mathfrak{B}=(B, h, g) \mid=x \tilde{\varphi}$. Construct $\mathfrak{A}=\left(A, f_{1}, \ldots, f_{m}\right)$ with

$$
\begin{aligned}
& -A=\{h b: b \in B\} \\
& -f_{i}(a)=\left(h g^{i}\right)(a)
\end{aligned}
$$

Then $\mathfrak{A} \models \forall x \varphi$.
$" \Rightarrow "$ Let $\mathfrak{A}=\left(A, f_{1}, \ldots, f_{m}\right) \models \forall x \varphi$. Construct $\mathfrak{B}=(B, g, h)$ with

$$
-B=A \times(\mathbb{Z} /(m+1) \mathbb{Z})
$$

$$
-g(a, i)=(a, i+1)
$$

$$
-h(a, 0)=(a, 0)
$$

$$
-h(a, i)=\left(f_{i} a, 0\right)
$$

This transformation preserves the meaning of terms: Let $t(x)=$ $f_{i_{1}} \ldots f_{i_{k}} x$ be a term in $\varphi$. Then $\tilde{t}(x)=h g^{i_{1}} \ldots h g^{i_{k}} h x$, and it holds that $\tilde{t}^{\mathfrak{B}}[a, 0]=\left(t^{\mathfrak{A}}[a], 0\right)$. Now the claim follows via induction over the structure of $\varphi$.

We now show that we need at most one binary function. The idea is to find an interpretation of $g, h: A \rightarrow A$ in a structure $\mathfrak{A}=(A, F)$ with $F: A \times A \rightarrow A$ via

- $g(a)=F(a, F(a, a))$,
- $h(a)=F(F(a, a), a)$
where $F(a, a) \neq a$.
Formally, consider a formula $\forall x \varphi$ with unary function symbols
$f, g$. Introduce a new binary function symbol $F$ and translate

$$
\varphi \mapsto \varphi_{g} \wedge \varphi_{h}
$$

where

$$
\begin{aligned}
\varphi_{g} & :=\varphi\left[x / g^{*} x, g / g^{*}, h / h^{*}\right], \\
\varphi_{h} & :=\varphi\left[x / h^{*} x, g / g^{*}, h / h^{*}\right]
\end{aligned}
$$

with

$$
\begin{aligned}
& g^{*} t=F(t, F t t), \\
& h^{*} t=F(F t t, t) .
\end{aligned}
$$

Claim: $\forall x \varphi$ (finitely) satisfiable $\Leftrightarrow \forall x\left(\varphi_{g} \wedge \varphi_{h}\right)$ (finitely) satisfiable.
$" \Rightarrow "$ Let $\mathfrak{A}=(A, g, h) \models \forall x \varphi$ be a model. Set $\mathfrak{B}=(B, F)$ with

- $B:=A \times \mathbb{Z} / 3 \mathbb{Z}$
$-F((a, i),(a, i)):=(a, i+1)$
$-F((a, i),(a, i+1)):=(g a, 0)$
$-F((a, i+1),(a, i)):=(h a, 0)$.
Now, for all $(a, i) \in B$

$$
g^{*}(a, i)=F((a, i), F(a, i)(a, i))=F((a, i),(a, i+1))=(g a, 0)
$$

and

$$
h^{*}(a, i)=(h a, 0)
$$

Thus $\mathfrak{A}$ is isomorphic to a copy of $\mathfrak{A}$ defined in $\mathfrak{B}$.

$$
\mathfrak{A} \cong \mathfrak{A}^{*}:=\left(\{(a, 0): a \in A\}, g^{*}, h^{*}\right)
$$

Therefore, for all $(a, i)$

$$
\mathfrak{B} \models \varphi_{g}(a, i) \Leftrightarrow \mathfrak{A}^{*} \models \varphi(g a, 0)
$$

$$
\begin{aligned}
& \Leftrightarrow \mathfrak{A} \mid=\varphi(g a) \quad \text { and } \\
\mathfrak{B} \models \varphi_{h}(a, i) & \Leftrightarrow \mathfrak{A}^{*}=\varphi(h a, 0) \\
& \Leftrightarrow \mathfrak{A} \mid=\varphi(h a) .
\end{aligned}
$$

Thus, $\mathfrak{A}=\forall x \varphi$ implies $\mathfrak{B} \models \forall x\left(\varphi_{g} \wedge \varphi_{k}\right)$.
$" \Leftarrow "$ For $\mathfrak{B}=(B, F) \mid \forall x\left(\varphi_{g} \wedge \varphi_{h}\right)$ let $\mathfrak{A}=(A, g, h)$ with
$-A:=g^{*}(B) \cup h^{*}(B)$
$-g:=g^{*}$
$-h:=h^{*}$
Then $\mathfrak{A} \models \forall x \varphi$.

